

Stochastic Programming: A tutorial – part II

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Applicability

Two-stage linear stochastic programs with recourse where

- ▶ ξ is a discrete random variable,
- ▶ $\mathcal{X} = \mathbb{R}_+^{n_1}$,
- ▶ $\mathcal{Y} = \mathbb{R}_+^{n_2}$.

The integer case requires some adjustments.

Recall

The deterministic equivalent problem

$$\begin{aligned} \min z &= c^T x + Q(x) \\ \text{s.t. } Ax &= b \\ x &\geq 0 \end{aligned}$$

where

$$Q(x) = \sum_{s=1}^S \pi_s Q(x, \xi_s)$$

and

$$Q(x, \xi_s) = \min_y \{q_s^T y \mid W_s y = h_s - T_s x, y \geq 0\}.$$

Recall

$$\mathcal{K}_1 = \{x \mid Ax = b, x \geq 0\}$$

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$$\mathcal{K}_2(\xi_s) = \{x \mid \exists y \geq 0, \text{ s.t. } W_s y = h_s - T_s x\}$$

$$\mathcal{K}_2 = \bigcap_{\xi \in \Xi} \mathcal{K}_2(\xi)$$

Recall

$$\mathcal{K}_1 = \{x | Ax = b, x \geq 0\}$$

$$\mathcal{K}_2(\xi_s) = \{x | \exists y \geq 0, \text{ s.t. } W_s y = h_s - T_s x\}$$

$$\mathcal{K}_2 = \bigcap_{\xi \in \Xi} \mathcal{K}_2(\xi)$$

- ▶ \mathcal{K}_2 is a closed and convex polyhedron
- ▶ $Q(x)$ is piecewise linear and convex in x

This will help..

A reformulation of the DEP

$$\begin{aligned} \min z &= c^T x + Q(x) \\ \text{s.t. } x &\in \mathcal{K}_1 \cap \mathcal{K}_2 \end{aligned}$$

A reformulation of the DEP

If we introduce a variable ϕ we can obtain another reformulation

$$\min z = c^T x + \phi$$

$$\text{s.t. } x \in \mathcal{K}_1$$

$$x \in \mathcal{K}_2$$

$$\phi \geq Q(x)$$

A reformulation of the DEP

Polyhedral formulation, but with way too many constraints..

Idea! Drop $x \in \mathcal{K}_2$ and $\phi \geq Q(x)$ and reconstruct them iteratively... (We may not need all their constraints).

The Master Problem

At a generic iteration..

$$\min z = c^T x + \phi$$

$$\text{s.t. } x \in \mathcal{K}_1$$

$$f_i(x) \leq 0$$

$$i = 1, \dots, I,$$

$$g_j(x, \phi) \leq 0$$

$$j = 1, \dots, J$$

The Master Problem

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$$\text{s.t. } x \in \mathcal{K}_1$$

$$f_i(x) \leq 0$$

$$i = 1, \dots, I,$$

$$g_j(x, \phi) \leq 0$$

$$j = 1, \dots, J$$

Initially $I = J = 0$.

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Feasibility

At iteration ν we solve MP and find (x^ν, ϕ^ν) .

Does $x^\nu \in \mathcal{K}_2$? Let's check:

For each s we solve the *feasibility subproblem*.

Feasibility

$$\begin{aligned} F^P(x^v, \xi_s) = \min_{y, v^+, v^-} & e^T v^+ + e^T v^- \\ \text{s.t.} & W_s y + I v^+ - I v^- = h_s - T_s x^v, \\ & y, v^+, v^- \geq 0 \end{aligned}$$

where $e^T = (1, \dots, 1)$ and I is the identity matrix.

Feasibility

$$F^P(x^v, \xi_s) = \min_{y, v^+, v^-} e^T v^+ + e^T v^-$$
$$\text{s.t. } W_s y + I v^+ - I v^- = h_s - T_s x^v,$$
$$y, v^+, v^- \geq 0$$

where $e^T = (1, \dots, 1)$ and I is the identity matrix.

Find the differences:

$$Q(x^v, \xi_s) = \min_y \{q_s^T y \mid W_s y = h_s - T_s x^v, y \geq 0\}.$$

Feasibility

$$F^P(x^v, \xi_s) = \min_{y, v^+, v^-} \{e^\top v^+ + e^\top v^- \mid W_s y + l v^+ - l v^- = h_s - T_s x^v, y, v^+, v^- \geq 0\}$$

Its dual

$$F^D(x^v, \xi_s) = \max_{\sigma} \{\sigma^\top (h_s - T_s x^v) \mid \sigma^\top W_s \leq 0, \sigma^\top l \leq e^\top, -\sigma^\top l \leq e^\top\}$$

Both are always feasible. Strong duality $F^D(x^v, \xi_s) = F^P(x^v, \xi_s)$.

Feasibility

If $F^P(x^v, \xi_s) = F^D(x^v, \xi_s) = 0$ for all s then $x^v \in \mathcal{K}_2$ otherwise it does not.

Feasibility

If $F^P(x^v, \xi_s) = F^D(x^v, \xi_s) = 0$ for all s then $x^v \in \mathcal{K}_2$ otherwise it does not.

If $x^v \notin \mathcal{K}_2$ we need to tell MP that x^v is not a good solution and must be cut off.

Feasibility

Consider solution x^v to MP. If $F^D(x^v, \xi_s) > 0$ for some s , let σ_s^v be its optimal solution. Then, the inequality

$$(\sigma_s^v)^\top (h_s - T_s x) \leq 0$$

is violated by $x^v \notin \mathcal{K}_2$.

Proof

Feasibility

Adding inequality

$$(\sigma_s^v)^\top (h_s - T_s x) \leq 0$$

to MP will cut off solution x^v at the next iteration. We call it a *feasibility cut*.

Feasibility

Solution $x^j \in \mathcal{K}_2$ satisfies feasibility cuts

$$(\sigma_s^v)^\top (h_s - T_s x) \leq 0$$

Proof

Feasibility

Summary:

- ▶ we know how verify $x^v \in \mathcal{K}_2$,
- ▶ we know that $(\sigma_s^v)^\top (h_s - T_s x) \leq 0$ will cut off infeasible solution $x^v \notin \mathcal{K}_2$,
- ▶ we know that $(\sigma_s^v)^\top (h_s - T_s x) \leq 0$ will not cut off feasible solutions.

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Optimality

Assume (x^v, ϕ^v) is now such that

$$x^v \in \mathcal{K}_2$$

We should now verify whether

$$\phi^v \geq Q(x^v)$$

We need to calculate

$$Q(x^v) = \sum_{s=1}^S \pi_s Q(x^v, \xi_s)$$

Optimality

For $s = 1, \dots, S$ solve

$$Q^P(x^v, \xi_s) = \min_y \{q_s^\top y \mid W_s y = h_s - T_s x^v, y \geq 0\}$$

or its dual

$$Q^D(x^v, \xi_s) = \max_{\rho} \{\rho^\top (h_s - T_s x^v) \mid \rho^\top W_s \leq q_s^\top\}$$

Optimality

Observe:

- ▶ $Q^P(x^v, \xi_s)$ is feasible (and, we assume, bounded)
- ▶ $Q^P(x^v, \xi_s) = Q^D(x^v, \xi_s)$,
- ▶ $Q(x^v) = \sum_{s=1}^S \pi_s Q^P(x^v, \xi_s) = \sum_{s=1}^S \pi_s Q^D(x^v, \xi_s)$.

Optimality

If $\phi^v < Q(x^v)$, then (x^v, ϕ^v) violates

$$\phi \geq \sum_{s=1}^S \pi_s (\rho_s^v)^\top (h_s - T_s x)$$

where ρ_s^v is the optimal solution to $Q^D(x^v, \xi_s)$. Proof

Optimality

(x', ϕ') , such that $\phi' \geq Q(x')$, satisfies

$$\phi \geq \sum_{s=1}^S \pi_s (\rho_s^v)^\top (h_s - T_s x)$$

Proof

Optimality

Summarizing:

- ▶ We know how to check optimality,
- ▶ We know how to cut off (x^v, ϕ^v) such that $\phi^v < Q(x^v)$,
- ▶ We know that optimality cuts preserve (x^l, ϕ^l) such that $\phi^l \geq Q(x^l)$.

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Putting everything together

1. Solve MP (initially no cuts) to find (x^v, ϕ^v)

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2. For $s = 1, \dots, S$ solve $F^D(x^v, \xi_s)$
3. If $F^D(x^v, \xi_s) > 0$ for some s , add a feasibility cut and return to STEP 1.

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3. If $F^D(x^v, \xi_s) > 0$ for some s , add a feasibility cut and return to STEP 1.
4. For $s = 1, \dots, S$ solve $Q^D(x^v, \xi_s)$ and calculate $Q(x^v)$

Putting everything together

1. Solve MP (initially no cuts) to find (x^v, ϕ^v)
2. For $s = 1, \dots, S$ solve $F^D(x^v, \xi_s)$
3. If $F^D(x^v, \xi_s) > 0$ for some s , add a feasibility cut and return to STEP 1.
4. For $s = 1, \dots, S$ solve $Q^D(x^v, \xi_s)$ and calculate $Q(x^v)$
5. If $\phi^v \geq Q(x^v)$, STOP (x^v, ϕ^v) is optimal otherwise add an optimality cut and return to STEP 1.

A finite algorithm

The algorithm converges

- ▶ finitely many possible cuts
- ▶ if (at most) all cuts are available, the solution to MP is optimal.

Bounds

$$c^T x^v + \phi^v \leq z^* \leq c^T x^v + Q(x^v)$$

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Dealing with integers

Integer variables in the first stage

VS

Integer variables in the second stage

Dealing with integers

Integer variables in the first stage:

Embed the L-Shaped Method into Branch and Bound.

Dealing with integers

Integer variables in the second stage (and binary first stage):

Let $L \leq Q(x) \quad \forall x$

Dealing with integers

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Dealing with integers

Integer variables in the second stage (and binary first stage):

Let $L \leq Q(x) \quad \forall x$

Let x^v integer solution at node v

Let \mathcal{I}_v the indices for which $x^v = 1$

Dealing with integers

Integer variables in the second stage (and binary first stage):

$$\phi \geq (Q(x^v) - L) \left| \sum_{i \in \mathcal{I}_v} x_i - \sum_{i \notin \mathcal{I}_v} x_i \right| - (Q(x^v) - L)(|\mathcal{I}_v| - 1) + L$$

Dealing with integers

Integer variables in the second stage (and binary first stage):

How does it work?

$$x = x^v \implies \phi \geq Q(x^v)$$

$$x \neq x^v \implies \phi \geq L^v \leq L$$

Dealing with integers

Integer variables in the second stage (and binary first stage):

The bound can be improved by looking in the neighborhood of x^v .

Classical (duality based) L-Shaped cuts on the LP relaxation help a lot!

Exercise

Exercise (approx. 50 min)

<https://tinyurl.com/sptutorial3>

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Feasibility

If $F^D(x^v, \xi_s) > 0$ for some s , let σ_s^v be its optimal solution. The feasibility cut

$$(\sigma_s^v)^\top (h_s - T_s x) \leq 0$$

cuts off the second-stage-infeasible solution $x^v \notin \mathcal{K}_2$.

Proof.

Assume $x^v \notin \mathcal{K}_2 \rightarrow \exists s$ with $F^D(x^v, \xi_s) = F^P(x^v, \xi_s) > 0$

$$F^D(x^v, \xi_s) = (\sigma_s^v)^\top (h_s - T_s x^v) > 0$$

σ_s^v optimal to $F^D(x^v, \xi_s) \rightarrow x^v$ does not satisfy

$$(\sigma_s^v)^\top (h_s - T_s x) \leq 0$$



Feasibility

Solution $x^l \in \mathcal{K}_2$ satisfies feasibility cuts

$$(\sigma_s^v)^\top (h_s - T_s x) \leq 0$$

Proof.

Assume $x^l \in \mathcal{K}_2$, then

$$F^D(x^l, \xi_s) = F^P(x^l, \xi_s) = 0 \quad s = 1, \dots, S$$

Solution σ_s^v to $F^D(x^v, \xi_s)$ is feasible for problem $F^D(x^l, \xi_s)$ but not optimal.

$$0 = F^D(x^l, \xi_s) = (\sigma_s^l)^\top (h_s - T_s x^l) \geq (\sigma_s^v)^\top (h_s - T_s x^l)$$

. Thus $x^l \in \mathcal{K}_2$ does not violate the feasibility cut. □

Optimality

Proof optimality cuts.

Proof.

Assume $\phi^v < Q(x^v)$. Then we have

$$\phi^v < Q(x^v) = \sum_{s=1}^S \pi_s Q^D(x^v, \xi_s) = \sum_{s=1}^S \pi_s (\rho_s^v)^\top (h_s - T_s x^v)$$

ρ_s^v optimal for $Q(x^v, \xi_s)$. Constraint

$$\phi \geq \sum_{s=1}^S \pi_s (\rho_s^v)^\top (h_s - T_s x)$$

is not satisfied by (x^v, ϕ^v) . □

Back

Optimality

Proof.

Assume $\phi^l \geq Q(x^l)$

$$\phi^l \geq Q(x^l) = \sum_{s=1}^S \pi_s Q^D(x^l, \xi_s) = \sum_{s=1}^S \pi_s (\rho_s^l)^\top (h_s - T_s x^l)$$

$$\sum_{s=1}^S \pi_s (\rho_s^l)^\top (h_s - T_s x^l) \geq \sum_{s=1}^S \pi_s (\rho_s^v)^\top (h_s - T_s x^l)$$

ρ_s^v is feasible for $Q^D(x^l, \xi_s)$ while ρ_s^l is optimal. Thus

$$\phi^l \geq \sum_{s=1}^S \pi_s (\rho_s^v)^\top (h_s - T_s x^l)$$

